

FireHub: A Space based Fire Management Hub

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BEYOND participated in the **Best Service Challenge Copernicus -Masters competition**

Submitted Service : The Operational EO based fire management service, known as:



"FireHub: A Space Based Fire Management Hub"

The service consists of four pillars:

- 1. The early fire detection and real-time fire monitoring
- 2. The large scale Burnt Scar Mapping during and after wildfires
- 3. The diachronic BSM and damage assessment
- 4. The hourly forecasting of fire smoke dispersion





ONE step... BEYOND Workshop , 15 October 2015, ESRIN, Frascati, Italy

"FireHub: A Space Based Fire Management Hub "

FireHub





Institutional End Users and stakeholders receiving the fire disaster services:







- S The European Copernicus Program (EMS service)
- S The Hellenic Fire Brigades Operations' Control Room
- S The Ministry of Env. (Directorate for Forests Protection
- S The Gen. Sec. Civil Protection
- **S** The Forestry Services over Greece and Europe
- S The National Cadastral Organisation
- Some the second state of the second state o
- S The Greek Army
- S The Public
- Some state of the service of the
- Some the BBU Research Center for Disaster Management- Romania
- S The European Fire Monitoring Center









Active Fire Detection by MSG SEVIRI Instrument



1	VIS0.6	0.635	0.56	0.71	
2	VISO.8	0.81	0.74	0.88	
3	NIR1.6	1.64	1.50	1.78	
4	IR3.9	3.90	3.48	4.36	
5	WV6.2	6.25	5.35	7.15	
6	WV7.3	7.35	6.85	7.85	
7	IR8.7	8.70	8.30	9.1	
8	IR9.7	9.66	9.38	9.94	
9	IR10.8	10.80	9.80	11.80	
10	IR12.0	12.00	11.00	13.00	
11	IR13.4	13.40	12.40	14.40	
12	HRV	Broadband (about 0.4 - 1.1 µ			

Surface, clouds, wind fields Surface, clouds, wind fields Surface, cloud phase Surface, clouds, wind fields Water vapor, high level clouds, atmospheric instability Water vapor, atmospheric instability Surface, clouds, atmospheric instability Ozone Surface, clouds, wind fields, atmospheric instability Surface, clouds, atmospheric instability Cirrus cloud height, atmospheric instability Surface, clouds





Regional Real Time Fire Monitoring Service based on EUMETSAT MSG SEVIRI Data Monitoring





Raw resolution: 3.5x3.5 km wide pixel over entire

Refined resolution: 0.5x0.5 km wide pixel over entire Greece





Active Fire Detection by MSG SEVIRI Instrument

The best suited MSG SEVIRI Channels for active fire detection of forest and vegetation fuels and discrimination from ambient temperatures are:

Channel	Central Wavelength (µm)	Spectral Band (µm)	
IR 3.9	3.92	3.48 - 4.36	
IR 10.8	10.8	9.80 - 11.80	

Classification step #1: The EUMETSAT Fire mapping algorithm (FIR) is based on fixed thresholding approach, applied on the spectral bands **IR 3.9** and **IR10.8**. The FIR algorithm uses the following criteria to check for **potential fire and fire pixels**:

- 1. Brightness temperature of channel IR3.9 > threshold 1
- 2. Brightness temperature difference of channels IR3.9 and IR10.8 > threshold 2
- 3. Difference of the standard deviations of channel IR3.9 and IR10.8 > threshold 3
- 4. Standard deviation of channel IR3.9 > threshold 4
- 5. Standard deviation of channel IR10.8 < threshold 5

(all standard deviations are computed over a 3x3 pixel group)

MSc in Space Science Technologies and Applications



CLASSIFICATION PROCESS

Classification enhancement # 1: The thresholds are dynamically changing calculated for each image and every pixel location on the basis of the seasonally variations and time depended Solar Zenith Angle.

Classification enhancement # 2 : Create and integrate classification evidence through geospatial ontology schemes and reasoning queries, accounting for the

- a) thematic consistency by eliminating false alarms
- **b)** account for the time persistence of the fire observations









The FIREHUB System

Data Import

- Extention module in MonetDB to load HRIT file into an SQL table or SciQL array
- HRIT_load_image(URIs) function

Product generation

- SciQL query that outputs a polygon to WKT format
- Final products in raster and shapefile formats

Classification

 Assign each pixel a fire non-fire flag with an associated level of confidence, via index thresholding

IAASARS

• Uses a 3x3 window

Georeferencing

- Initial transformation by hand
- Concise implementation using SciQL

MSc in Space Science Technologies and Applications



Regional Real Time Fire Monitoring - NOA's MSG SEVIRI Station – Raw Resolution mode



SEVIRI MIR 070823_1030 UTC

POTENTIAL FIRE



CLASSIFICATION PROCESS

Classification enhancement # 3: Downscaling the first classification output and calculate the fire occurrence probability in sub-areas of 500 m x 500 m wide, inside the initial observation area of 3.5km x 3.5 km, accounting for the real meteorological, physical / ecological, and morphological conditions in the affected area such as,

a) Wind conditions (speed/direction), **b)** Fuel types and fuel type's proneness to fire, **c)** Altitudinal zone, **d)** Slope and Aspect elements of each of the 500m x500m area.



Results @ 150 minutes after fire ignition

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FLEXPART – NOA

Biomass Burning (Organic Carbon – OC)

FLEXPART - NOA Biomass Burning (Organic Carbon -OC)

valid date:24-08-2011 09UTC Model layer: Integrated Column (ng m⁻³)

Valid Date:26-08-2007 0900UTC (ng m⁻³) 09:00 UTC Model layer: Integrated Column 25°30'E 26°E 26°30'E 24°20'E EXPART NOA 145 370 445 500 295 mass Burning (Organic Carbon -OC) ng m-3 te:24-8-2011 09UTC 500 470 420 :00 UTC 370 320 270 220 170 28°E 20°E 22°E 24°E 26°E 120 70 20 10 20 60 70 80 90 100 40.58, 25.27 40.71, 25.54 40.83, 25.82 0 30 40.96, 26.1 lat/lon along transect

FLEXPART - NOA Biomass Burning (Organic Carbon -OC)

FireHub

valid date:24-08-2011 10UTC Model layer: Integrated Column (ng m⁻³)

Rapid Mapping During Crisis - Off-line Mapping After Crisis

Fully Automatic Processing Chain

Applies to any type of High and Very High Resolution Satellite Data

(Landsat TM, SPOT XS, IKONOS, Formosat-2, Worldview, Quickbird)

Advanced Informatics Processing Languages Array Data Base processing - SciQL

Scientific Python, ontology schemes and ontology based queries for linking open geo-spatial data (e.g. geo-names, administrative boundaries)

(Single/multi-date) Burn Scar Mapping from reflected Near - Mid Infrared radiation captured by multispectral sensor systems

Landsat-7 E	TM+ Bands (µm)		Landsat-8 OLI and TIRS Bands (µm)		
			30 m Coastal/Aerosol	0.435 - 0.451	Band 1
Band 1	30 m Blue	0.441 - 0.514	30 m Blue	0.452 - 0.512	Band 2
Band 2	30 m Green	0.519 - 0.601	30 m Green	0.533 - 0.590	Band 3
Band 3	30 m Red	0.631 - 0.692	30 m Red	0.636 - 0.673	Band 4
Band 4	30 m NIR	0.772 - 0.898	30 m NIR	0.851 - 0.879	Band 5
Band 5	30 m SWIR-1	1.547 - 1.749	30 m SWIR-1	1.566 - 1.651	Band 6
Band 6	60 m TIR	10.31 - 12.36	100 m TIR-1	10.60 - 11.19	Band 10
			100 m TIR-2	11.50 - 12.51	Band 11
Band 7	30 m SWIR-2	2.064 - 2.345	30 m SWIR-2	2.107 - 2.294	Band 7
Band 8	15 m Pan	0.515 - 0.896	15 m Pan	0.503 - 0.676	Band 8
			30 m Cirrus	1.363 - 1.384	Band 9

Rapid Mapping During Crisis - Off-line Mapping After Crisis

BSM_NOA Pre- Processing

(1) Separate clouds from vegetation – Create water and shadow masks

(3) Perform sensor radiometric calibration and scene radiometric normalisation to create compatible time series of satellite image acquisitions for multi-date analysis

(4) Geo-reference the input satellite data using fully automatic image coregistration techniques with appropriate sensor geometric models

Rapid Mapping During Crisis - Off-line Mapping After Crisis

Vis & Near IR Spectral Signatures

BSM_NOA Processing

(1) Generate band transformation indices Normalised Burn Ratio Index, Albedo, NDVI, multi-date NDVI, NDVIdiff, multi-date derived Radiometric Change Vectors

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(2) Define appropriate image /sensor/land use dependent threshold values and apply to the band transformation indices in order to: a) identify yearly changed from unchanged areas due to fire disasters and other ecosystem disturbances, b) identify burnt spectra on the image plane, and c) resolve for open, urban, and less vegetative areas' confusion

Classification

Rapid Mapping During Crisis -Off-line Mapping After Crisis

BSM_NOA Post Processing

(1) Clean from isolated pixels, and small area classification noise using a 3x3 smoothing kernel, and proceed with the join of small disconnected fire pixel clubs to larger segments (>1ha). Filter out objects smaller than 1ha

(2) Convert raster fire classification layer to vector fire polygons and smooth the fire polygon boundaries to resolve from pixel effect

(3)Apply a series of geospatial reasoning queries in GIS using expert knowledge in order to generate refined classifications of Burnt Areas (based on knowledge extracted from over than 30 years of fire occurrence statistical observations)

(4)Assign attribute data to the fire vector polygons (administrative data, land cover data, toponyms, area (ha), perimeter, etc)

ONE step... BEYOND Workshop , 15 October 2015, ESRIN, Frascati, Italy

FireHub

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Map produced on 19 09 2011 by ISARS/NOA © NOA 2011

> European Commission

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OHSERVATORS OF

IAASARS

1) More than 700 Landsat TM images acquired over Greece in the period 1984-2014 residing on USGS archives were downloaded and processed fully automatically using the NOA processing chain.

2) Yearly maps of Burned Areas have been produced

3) Yearly statistics per land cover type and administrative data have been generated

4)On-line dissemination of the produced maps and statistics through the NOA's dedicated web interface

URL: http://www.noa.gr

01-08-2013

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ΚΑΤΑΣΤΑΣΗ ΔΑΣΙΚΩΝ ΠΥΡΚΑΓΙΩΝ

1) 25-30% of the detected fires are reported 10 -15 minutes earlier than Fire Brigades logs

2) 60% of the detected fires, are reported in the first ~15 minutes after the ignition time stamp reported in the Fire Brigade logs

3) All the larger fires than the 112ha are completely detected without any omission

4) Smaller fires, that are in the range of [4.7ha - 112 ha] are 50% detected

5) The smallest detected fire has been of the order of 4.7 ha

6) The omitted fire detections, are summing up to the 5,8% of the total Burned Area. Omissions are caused mainly due to, a) cloud cover, b) fire intensity (e.g. small fires – small burned areas), c) area topography, and d) fuel characteristics (e.g. less vegetative areas, pasture lands, sparse vegetation resulting in low fire intensities)

7) The 82-85% of the 500mx500m cells which are assigned a high fire occurrence probability that is in the range of [6, 10], are located in the Burned Area Polygons

Future Updates

Real time integration of active fire and burned area evidences, as soon as they are depicted (captured) on the scenes of polar satellite systems acquired on the BEYOND X-/L-band acquisition station (EOS, NPP, NOAA/AVHRR, METOP)

Real time integration of in-field crowd source evidence (e.g. fire locations, and ignition points) returned from the Fire Brigade teams during crisis

Ingest the additional bits of evidence in an assimilation process for deriving more accurate FIREHUB assessments (fire occurrences)

Use mobile platforms for informing about the fire occurrences in addition to the web platform

Expand the FIREHUB concept to other hazards (Floods, & EQs)

FireHub

DisasterHub

European

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BECOND FireHub

FireHub

A Space based Fire Management Hub

Thank you for your attention!

For more information

ocean.space.noa.gr/FireHub

